1. Open the “Read Data Action” library: *read_mini_actions*
    a. Write down the servo angles for an action group that switches the order of two blocks stacked on top of each other

2. Open “Run Action Group” library: *mini_actions_group*
    a. Write your servo angles from above into the *actions.h* header file
    b. Adjust the servo angles so that the order of the blocks is successfully switched
    c. In the `user_task` function comment out the following line to run your action group continuously:

```
// step = 1;
```